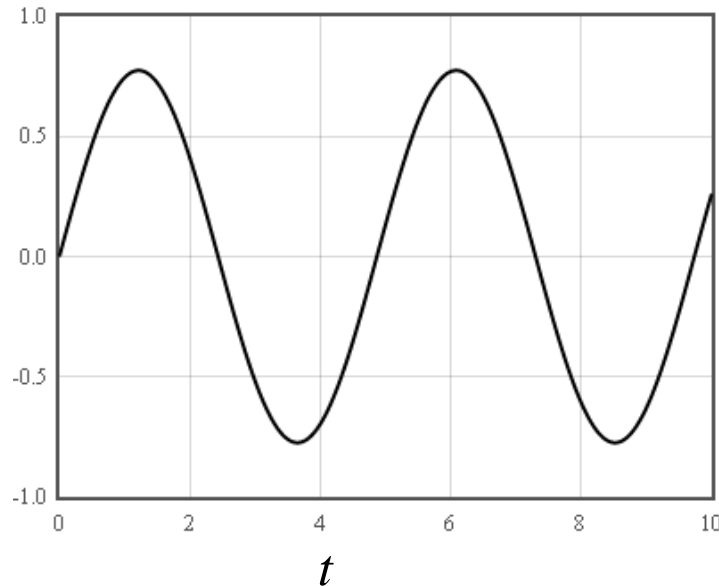


Harmonische Schwingung

$$f = \frac{1}{T}$$



sinusförmig = harmonisch

$$\sin(\omega t + \theta)$$

← Radiant

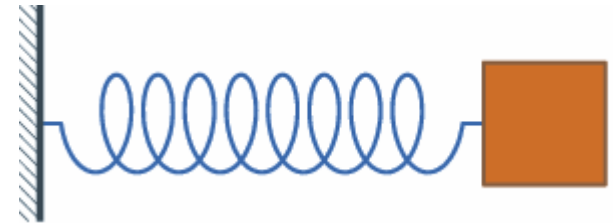
Kreisfrequenz

$$\omega = 2\pi f = \frac{2\pi}{T}$$

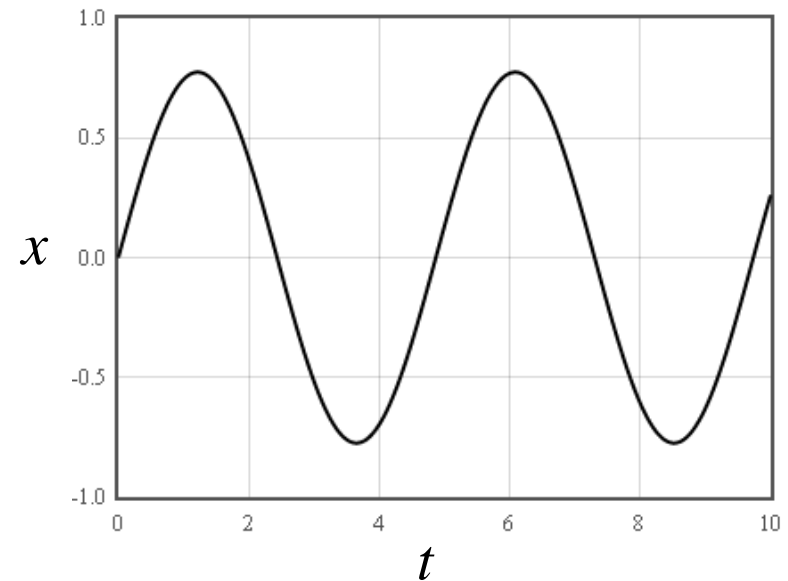
rad/s

Freie Schwingung

$$m \frac{d^2 x}{dt^2} = -kx$$



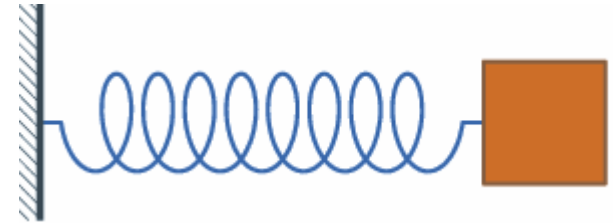
Lösung: $x(t) = C_1 \sin(\omega_0 t) + C_2 \cos(\omega_0 t)$



$$\omega_0 = ?$$

Freie Schwingung

$$m \frac{d^2 x}{dt^2} = -kx$$



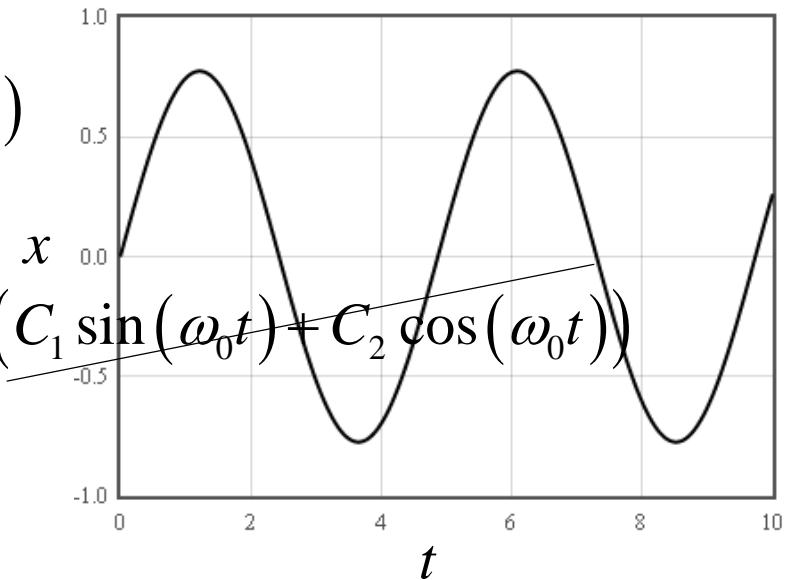
$$x(t) = C_1 \sin(\omega_0 t) + C_2 \cos(\omega_0 t)$$

$$\frac{d^2 x}{dt^2} = -\omega_0^2 C_1 \sin(\omega_0 t) - \omega_0^2 C_2 \cos(\omega_0 t)$$

~~$$-m\omega_0^2 (C_1 \sin(\omega_0 t) + C_2 \cos(\omega_0 t)) = -k (C_1 \sin(\omega_0 t) + C_2 \cos(\omega_0 t))$$~~

$$m\omega_0^2 = k$$

$$\omega_0 = \sqrt{\frac{k}{m}}$$



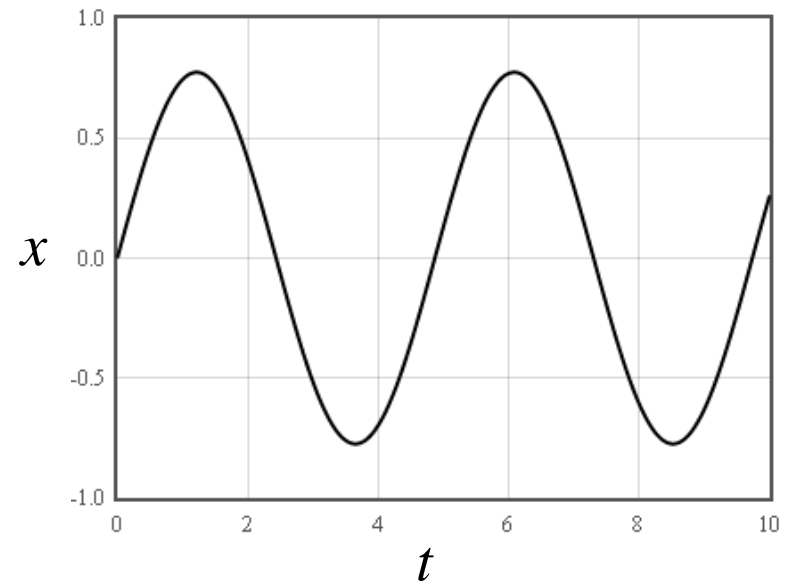
Anfangsbedingungen

$$x(t = 0) = 0$$

$$\frac{dx}{dt}(t = 0) = 1$$

$$x(t) = C_1 \sin(\omega_0 t) + C_2 \cos(\omega_0 t)$$

$$\frac{dx}{dt} = \omega_0 C_1 \cos(\omega_0 t) - \omega_0 C_2 \sin(\omega_0 t)$$



$$x(t = 0) = 0 = C_2$$

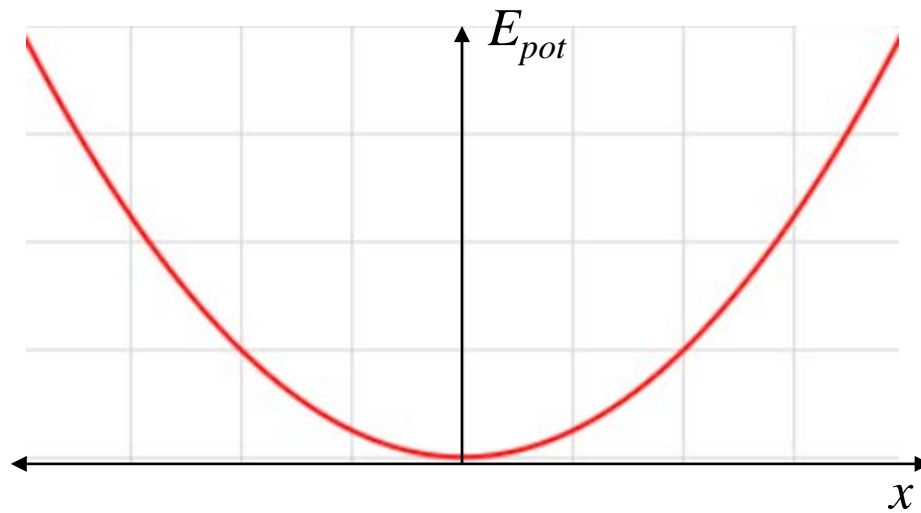
$$C_2 = 0$$

$$\frac{dx}{dt}(t = 0) = 1 = \omega_0 C_1$$

$$C_1 = \frac{1}{\omega_0}$$

andere Schwingungssysteme

E_{pot} hat ein Minimum bei dem Gleichgewichtspunkt



$$F_x = -\frac{dU}{dx}$$

Pendel

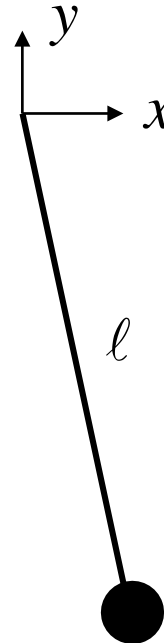
$$x^2 + y^2 = \ell^2$$

$$E_{pot} = -mgy = -mg\sqrt{\ell^2 - x^2}$$

$$F_x = -\frac{\partial E_{pot}}{\partial x} = \frac{1}{2} \frac{mg(-2x)}{\sqrt{\ell^2 - x^2}}$$

für $x \ll y \approx \ell$

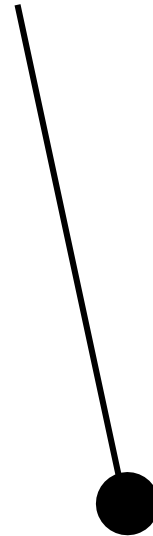
$$F_x \approx -\frac{mgx}{\ell}$$



Pendel

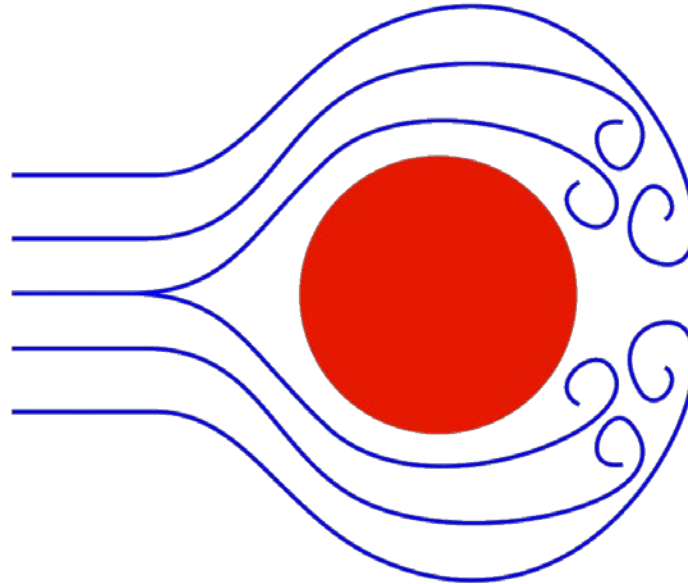
$$m \frac{d^2 x}{dt^2} \approx -\frac{mg}{l} x$$

$$\omega_0 = \sqrt{\frac{g}{l}}$$



Reibungskraft (Strömungswiderstand)

$$\vec{F} = -a\vec{v} - b\vec{v} |\vec{v}| - c\vec{v} |\vec{v}|^2 + \dots$$



$$F_x \approx -a \frac{dx}{dt}$$


Schwingungssysteme

für kleine Amplitudenschwankungen und niedrigen Geschwindigkeiten die Differentialgleichung für eine schwingende Systeme ist

$$a \frac{d^2 x}{dt^2} + b \frac{dx}{dt} + cx = d$$


Lineare gewöhnliche Differentialgleichung zweiter Ordnung


Lineare gewöhnliche Differentialgleichung

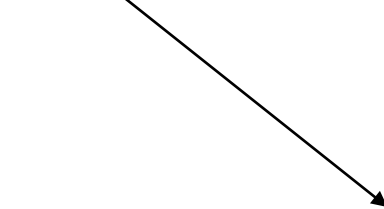
$$m \frac{d^2 x}{dt^2} + b \frac{dx}{dt} + kx = 0$$


Lineare Differentialgleichung zweiter Ordnung

Nichtlineare
Differentialgleichung
zweiter Ordnung


$$m \left(\frac{d^2 x}{dt^2} \right)^2 + b \frac{dx}{dt} + kx = 0$$


$$m \frac{d^2 x}{dt^2} + b \left(\frac{dx}{dt} \right)^2 + kx = 0$$


$$m \frac{d^2 x}{dt^2} + b \frac{dx}{dt} + kx^3 = 0$$

$$m \frac{d^2 x}{dt^2} + b \frac{dx}{dt} + kx = 0$$

$$a_x = -\frac{b}{m} v_x - \frac{k}{m} x$$

Numerical 2nd order differential equation solver

$$\frac{dx}{dt} = v_x$$

$$a_x = \frac{F_x}{m} = \frac{dv_x}{dt} = -50*x*abs(x)$$

Initial conditions:

$$x(t_0) = 0.02$$

$$\Delta t = 0.05$$

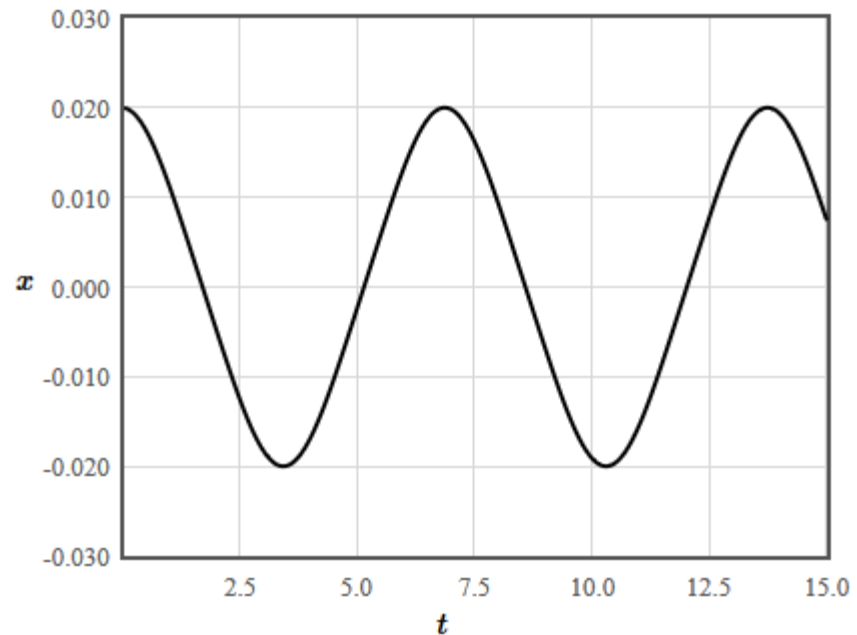
$$v_x(t_0) = 0$$

$$N_{steps} = 300$$

$$t_0 = 0$$

Plot: x vs. t

submit



Differentialgleichungen zweiter Ordnung

Lösung Differentialgleichungen zweiter Ordnung

$$a \frac{d^2 x}{dt^2} + b \frac{dx}{dt} + cx = d,$$

$$a = \text{1}$$

$$b = \text{3}$$

$$c = \text{1}$$

$$d = \text{0}$$

Anfangsbedingungen:

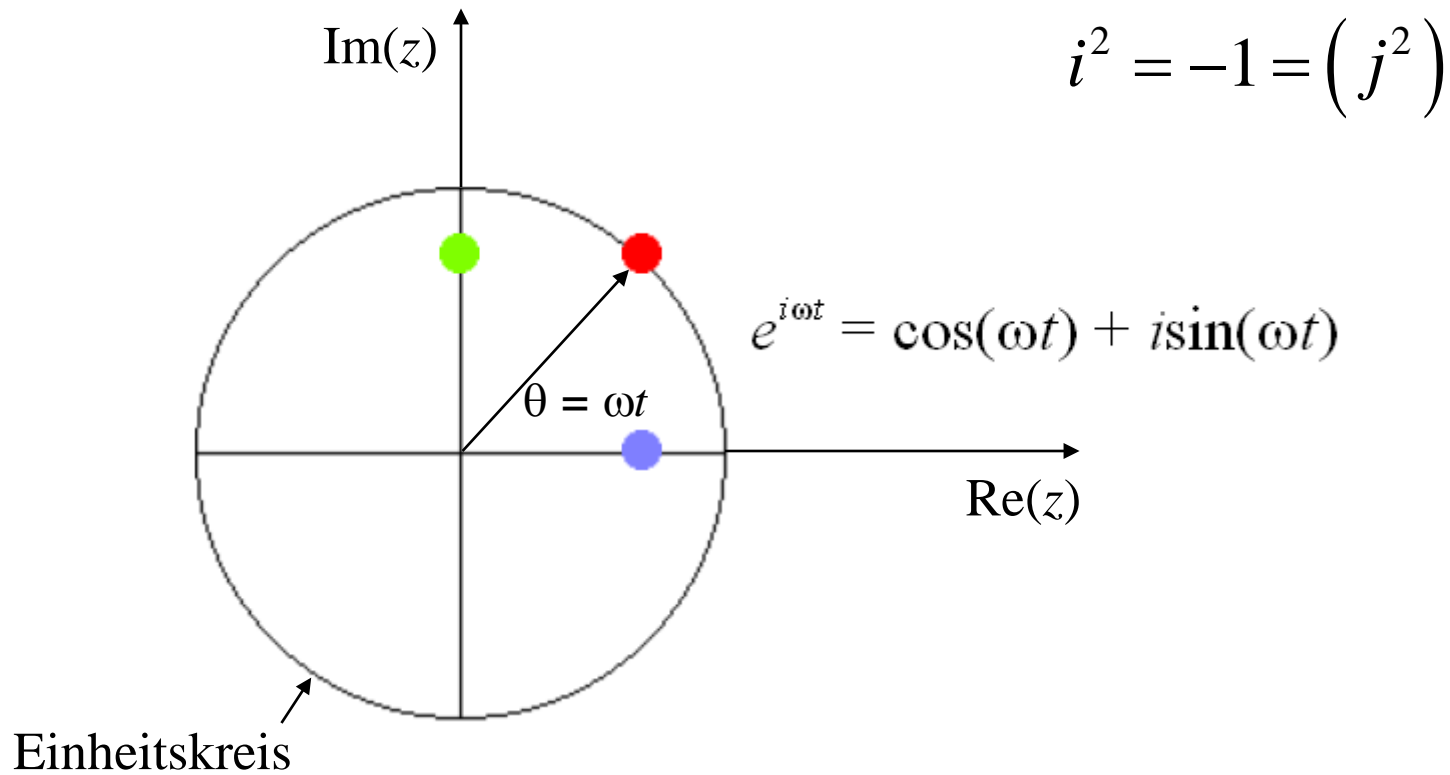
$$x(t_0) = \text{1}$$

$$\frac{dx}{dt}(t_0) = \text{0}$$

$$t_0 = \text{0}$$

Lösung

Euler'sche Formel $e^{i\theta} = \cos\theta + i\sin\theta$



$\omega = \text{Kreisfrequenz}$

$$|e^{i\theta}| = \sqrt{e^{-i\theta} e^{i\theta}} = \sqrt{e^0} = 1 = \sqrt{(\cos\theta - i\sin\theta)(\cos\theta + i\sin\theta)} = \sqrt{\cos^2\theta + \sin^2\theta} = 1$$

Lineare gewöhnliche Differentialgleichung

$$m \frac{d^2 x}{dt^2} + b \frac{dx}{dt} + kx = 0$$

Lösung: $x = Ce^{\lambda t}$



Konstant

$$m\lambda^2 Ce^{\lambda t} + b\lambda Ce^{\lambda t} + kCe^{\lambda t} = 0$$

$$m\lambda^2 + b\lambda + k = 0$$

Lineare gewöhnliche Differentialgleichung

$$m\lambda^2 + b\lambda + k = 0$$

$$\lambda_1 = \frac{-b + \sqrt{b^2 - 4mk}}{2m} \quad \lambda_2 = \frac{-b - \sqrt{b^2 - 4mk}}{2m}$$

Lösung: $x(t) = C_1 e^{\lambda_1 t} + C_2 e^{\lambda_2 t}$

$$x(0) = C_1 + C_2$$

Anfangsbedingungen:

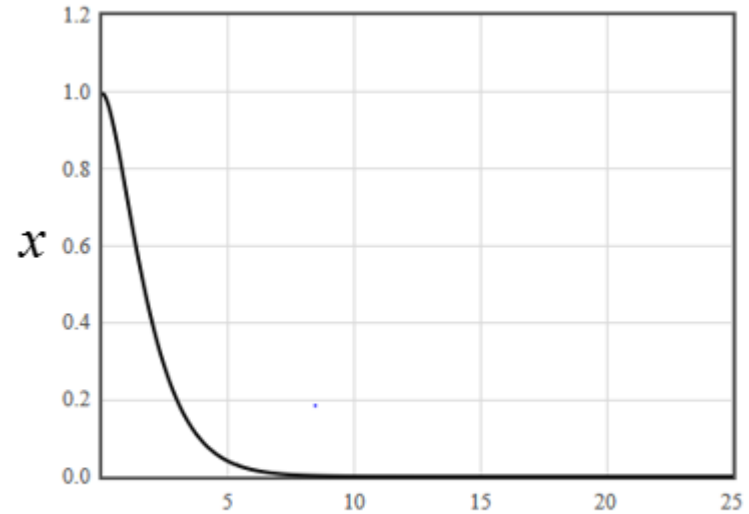
$$\frac{dx}{dt}(0) = \lambda_1 C_1 + \lambda_2 C_2$$

$$C_1 = \frac{\lambda_2 x(0) - \frac{dx}{dt}(0)}{\lambda_2 - \lambda_1}$$

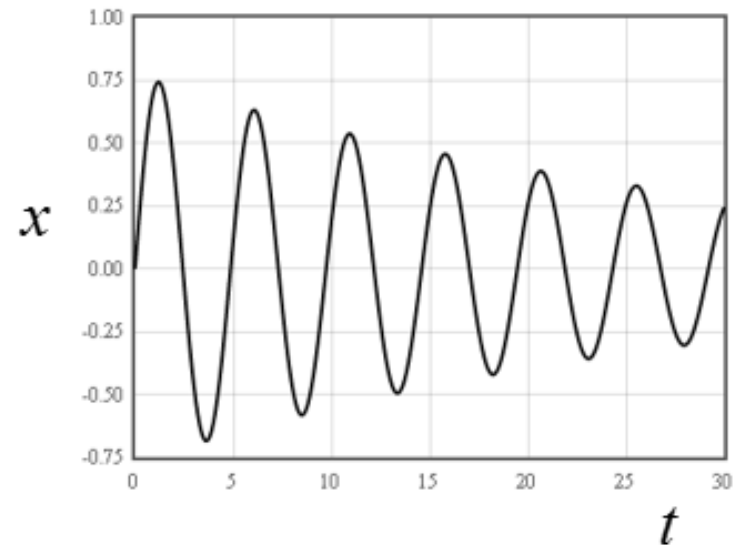
$$C_2 = \frac{\lambda_1 x(0) - \frac{dx}{dt}(0)}{\lambda_1 - \lambda_2}$$

$$\lambda = \frac{-b \pm \sqrt{b^2 - 4mk}}{2m}$$

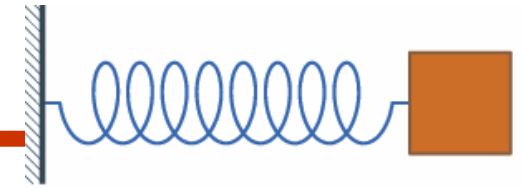
$b^2 > 4km$ Kriechfall



$b^2 < 4km$ Schwingfall



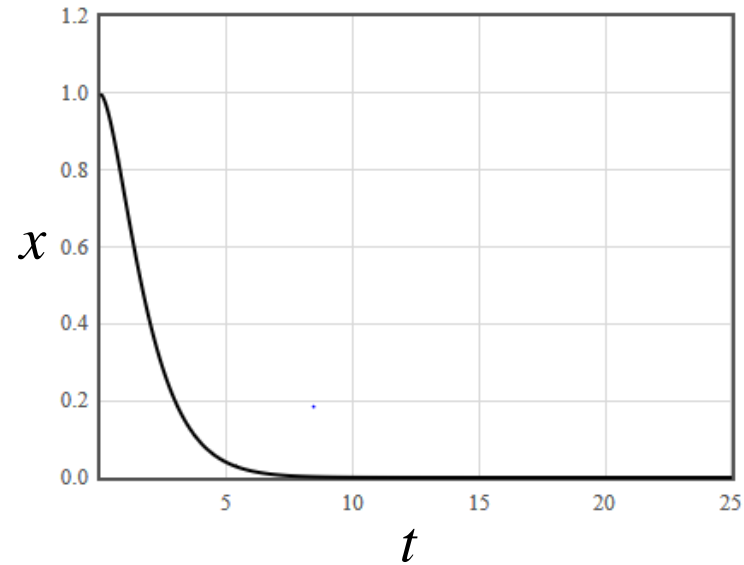
$b^2 > 4km$ Kriechfall



$$m \frac{d^2 x}{dt^2} + b \frac{dx}{dt} + kx = 0$$

Lösung: $x(t) = C_1 e^{\lambda_1 t} + C_2 e^{\lambda_2 t}$

$$\lambda_{1,2} = \frac{-b \pm \sqrt{b^2 - 4mk}}{2m}$$



$$x(t) = C_1 \exp(-t / \tau_1) + C_2 \exp(-t / \tau_2)$$

$$\tau_1 = \frac{-1}{\lambda_1} = \frac{2m}{b + \sqrt{b^2 - 4km}}$$

$$\tau_2 = \frac{-1}{\lambda_2} = \frac{2m}{b - \sqrt{b^2 - 4km}}$$